

Varieties of Signature Tensors

Lecture #1

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Setup: Signatures

- Let $X : [0, 1] \rightarrow \mathbb{R}^d$ be a piecewise differentiable [path](#).
- Coordinate functions: $X_1, X_2, \dots, X_d : \mathbb{R} \rightarrow \mathbb{R}$
- Their differentials $dX_i(t) = X_i'(t)dt$ are the coordinates of the vector

$$dX = (dX_1, dX_2, \dots, dX_d)$$

- The [kth signature](#) of X is a **tensor** $\sigma^{(k)}(X)$ of order k and format $d \times d \times \dots \times d$. It is the multivariate integral:

$$\sigma^{(k)}(X) = \int_{\Delta} dX(t_1) \otimes dX(t_2) \otimes \dots \otimes dX(t_k),$$

where $\Delta = \{(t_1, t_2, \dots, t_k) \in \mathbb{R}^k : 0 \leq t_1 \leq t_2 \leq \dots \leq t_k \leq 1\}$.

- Its d^k entries $\sigma_{i_1 i_2 \dots i_k}$ are the *iterated integrals*

$$\sigma_{i_1 i_2 \dots i_k} = \int_0^1 \int_0^{t_k} \dots \int_0^{t_3} \int_0^{t_2} dX_{i_1}(t_1) dX_{i_2}(t_2) \dots dX_{i_k}(t_k).$$

- $\sigma^{(k)}(X)$ has entries

$$\sigma_{i_1 i_2 \dots i_k} = \int_0^1 \int_0^{t_k} \dots \int_0^{t_3} \int_0^{t_2} dX_{i_1}(t_1) dX_{i_2}(t_2) \dots dX_{i_k}(t_k).$$

- Let's start with $k = 1$:
- Fundamental Theorem of Calculus:

$$\int_0^1 dX_i(t) = X_i(1) - X_i(0)$$

- The **first signature** of the path X is

$$\sigma^{(1)}(X) = \int_0^1 dX(t) = X(1) - X(0) \in \mathbb{R}^d$$

Signature Matrices

- Now let's consider $k = 2$. Then the **second signature** $S = \sigma^{(2)}(X)$ is the $d \times d$ matrix with entries

$$\sigma_{ij} = \int_0^1 \int_0^t dX_i(s) dX_j(t)$$

- Set $X(0) = 0$. Applying Fundamental Theorem of Calculus again:

$$\sigma_{ij} = \int_0^1 X_i(t) X_j'(t) dt$$

- We obtain

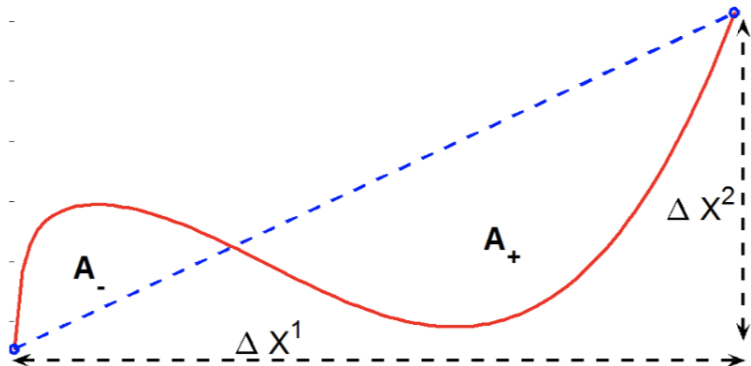
$$\sigma_{ij} + \sigma_{ji} = X_i(1) \cdot X_j(1)$$

- In matrix notation, $S + S^T = X(1) \cdot X(1)^T$
- In particular, the symmetric matrix $S + S^T$ has rank **one**!
- The skew-symmetric matrix $S - S^T$ measures *deviation from linearity*:

$$\sigma_{ij} - \sigma_{ji} = \int_0^1 (X_i(t) X_j'(t) - X_j(t) X_i'(t)) dt$$

Lévy Area

The entry $\sigma_{ij} - \sigma_{ji}$ of the skew-symmetric matrix $S - S^T$ is the area below the line minus the area above the line, known as a **Lévy area**:



Some History

- Introduced by Kuo Tsai Chen in the 1950s:
K.-T. Chen: *Integration of paths, geometric invariants and a generalized Baker-Hausdorff formula*, Annals of Mathematics **65** (1957)
K.-T. Chen: *Integration of paths a faithful representation of paths by noncommutative formal power series*, Transactions AMS **89** (1958)

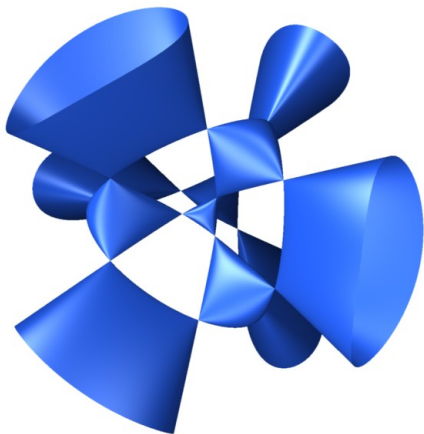
- The *signature* of a path X is the sequence of tensors

$$\sigma(X) = (1, \sigma^{(1)}(X), \sigma^{(2)}(X), \sigma^{(3)}(X), \dots, \sigma^{(n)}(X), \dots)$$

- *Essential question*: how much information does the signature reveal about the path X ?
- Signature determines paths! (modulo starting point, parametrization and tree-like excursion)
B. Hambly and T. Lyons: *Uniqueness for the signature of a path of bounded variation and the reduced path group*, Annals of Mathematics **171** (2010)

- Signatures are central to the theory of **rough paths**, a revolutionary view on *Stochastic Analysis*.
- P. Friz and N. Victoir: *Multidimensional Stochastic Processes as Rough Paths*. Theory and Applications, Cambridge University Press, 2010.
P. Friz and M. Hairer: *A Course on Rough Paths*. With an introduction to regularity structures, Universitext, Springer, Cham, 2014.
- They can be used to encode and model **data!**
T. Lyons: *Rough paths, signatures and the modelling of functions on streams*, Proc. International Congress of Mathematicians 2014, Seoul
I. Chevyrev and A. Kormilitzin: *A primer on the signature method in machine learning*, arXiv:1603.03788.

- What happens when **signatures** meet **Algebraic Statistics**?
- C. Améndola, P. Friz and B. Sturmfels: *Varieties of Signature Tensors*, arXiv:1804.08325.
- M. Pfeffer, A. Seigal and B. Sturmfels: *Learning Paths from Signature Tensors*, arXiv:1809.01588.
- F. Galuppi: *The Rough Veronese Variety*, arXiv:1809.02522.
- L. Colmenajero and M. Michalek: *Signature Varieties of Axis Paths*, in preparation.
- **YOUR** papers on signatures!
- We are interested in projective **varieties** in tensor space \mathbb{P}^{d^k-1} that arise when X ranges over some nice families of paths.



$$x^4 + y^4 + z^4 - x^2 - y^2 - z^2 - x^2y^2 - x^2z^2 - y^2z^2 + 1 = 0$$

Algebraic Varieties

- Solution set of a polynomial system of equations.
- $\mathcal{V} \subseteq K^d$ (affine) algebraic variety \Rightarrow we can find a set of polynomials $F \subseteq \mathbb{K}[s_1, \dots, s_d]$ such that

$$\mathcal{V} = \{a \in \mathbb{K}^d \mid f(a) = 0 \text{ for all } f \in \mathcal{F}\}$$

- If polynomials are homogeneous \Rightarrow work in projective space \mathbb{P}^{d-1} .
- The ideal V associated to a variety \mathcal{V} : set of all polynomials that vanish on \mathcal{V} .
- Key Fact: a polynomial map $\sigma : \mathbb{K}^m \rightarrow \mathbb{K}^d$ induces naturally an algebraic variety that contains the image of σ .

Example of a Signature Variety

- Let $d = 2$ and consider **quadratic paths** in the plane \mathbb{R}^2 :

$$X(t) = (x_{11}t + x_{12}t^2, x_{21}t + x_{22}t^2)^T = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \cdot \begin{pmatrix} t \\ t^2 \end{pmatrix}$$

- Their k th signature tensors depend **polynomially** of degree k on x_{ij} .
- $\sigma^{(1)}(X) = (\sigma_1, \sigma_2) = (x_{11} + x_{12}, x_{21} + x_{22})$.

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$$\begin{aligned} \sigma_{ij} &= \int_0^1 \int_0^t (x_{i1} + 2x_{i2}s) ds (x_{j1} + 2x_{j2}t) dt \\ &= \int_0^1 (x_{i1}t + x_{i2}t^2) (x_{j1} + 2x_{j2}t) dt \\ &= \int_0^1 [x_{i1}x_{j1}t + (2x_{i1}x_{j2} + x_{i2}x_{j1})t^2 + 2x_{i2}x_{j2}t^3] dt \\ &= \frac{1}{2}x_{i1}x_{j1} + \frac{2}{3}x_{i1}x_{j2} + \frac{1}{3}x_{i2}x_{j1} + \frac{1}{2}x_{i2}x_{j2}. \end{aligned}$$

- We can write $\sigma^{(2)}(X)$ as

$$\frac{1}{2} \begin{pmatrix} x_{11} + x_{12} \\ x_{21} + x_{22} \end{pmatrix} (x_{11} + x_{12}, x_{21} + x_{22}) + \frac{1}{6} (x_{11}x_{22} - x_{12}x_{21}) \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

Example of a Signature Variety

- The variety of all such signature matrices is the solution set of the quadratic equation

$$(\sigma_{12} + \sigma_{21})^2 - 4\sigma_{11}\sigma_{22} = 0.$$

- This means that the image variety associated to signature matrices of polynomial paths of degree two in the plane is a hypersurface in \mathbb{P}^3 .
- We will denote this surface by $\mathcal{P}_{2,2,2}$. Its prime ideal generated by the quadric above is $P_{2,2,2}$.
- We want to study and *understand* these varieties!
- **Question:** What is the resulting variety if we restrict to **linear paths**?
- **Answer:** The **Veronese** variety!

- The third signature $\sigma^{(3)}(X)$ is a $2 \times 2 \times 2$ -tensor ($d = 2, k = 3$).

$$\sigma_{111} = \frac{1}{6}(x_{11} + x_{12})^3$$

$$\sigma_{112} = \frac{1}{6}(x_{11} + x_{12})^2(x_{21} + x_{22}) + \frac{1}{60}(5x_{11} + 4x_{12})(x_{11}x_{22} - x_{12}x_{21})$$

$$\sigma_{121} = \frac{1}{6}(x_{11} + x_{12})^2(x_{21} + x_{22}) + \frac{1}{60}(2x_{12})(x_{11}x_{22} - x_{12}x_{21})$$

$$\sigma_{211} = \frac{1}{6}(x_{11} + x_{12})^2(x_{21} + x_{22}) - \frac{1}{60}(5x_{11} + 6x_{12})(x_{11}x_{22} - x_{12}x_{21})$$

$$\sigma_{122} = \frac{1}{6}(x_{11} + x_{12})(x_{21} + x_{22})^2 + \frac{1}{60}(5x_{21} + 6x_{22})(x_{11}x_{22} - x_{12}x_{21})$$

$$\sigma_{212} = \frac{1}{6}(x_{11} + x_{12})(x_{21} + x_{22})^2 - \frac{1}{60}(2x_{22})(x_{11}x_{22} - x_{12}x_{21})$$

$$\sigma_{221} = \frac{1}{6}(x_{11} + x_{12})(x_{21} + x_{22})^2 - \frac{1}{60}(5x_{21} + 4x_{22})(x_{11}x_{22} - x_{12}x_{21})$$

$$\sigma_{222} = \frac{1}{6}(x_{21} + x_{22})^3$$

- Goal: find the polynomial relations among the eight entries of $\sigma^{(3)}(X)$
- Image signature variety is $\mathcal{P}_{2,3,2}$ and its prime ideal is $P_{2,3,2}$.
- An instance of the general $P_{d,k,m}$ of polynomial paths of degree m .

Some Favorite Tensors

- The *canonical axis path* C_{axis} in \mathbb{R}^d goes from $(0, 0, \dots, 0)$ to $(1, 1, \dots, 1)$ in d linear steps in unit directions e_1, e_2, \dots, e_d .
Exercise: What is $\sigma^{(k)}(C_{\text{axis}})$?
Hint: The entry $\sigma_{i_1 i_2 \dots i_k}$ is always zero unless $i_1 \leq i_2 \leq \dots \leq i_k$.
- The *canonical monomial path* C_{mono} in \mathbb{R}^d given by $t \rightarrow (t, t^2, t^3, \dots, t^d)$ goes from $(0, 0, \dots, 0)$ to $(1, 1, \dots, 1)$ along the rational normal curve.
Exercise: What is $\sigma^{(k)}(C_{\text{mono}})$?
- *Key observation:* We can compute the k th signature tensors of piecewise linear paths or polynomial paths just by knowing $\sigma^{(k)}(C_{\text{axis}})$ or $\sigma^{(k)}(C_{\text{mono}})$, respectively.
- *How?* Encode any such path as a matrix \mathbf{X} . The map $X \rightarrow \sigma^{(k)}(X)$ is then given by the **congruence** action $\mathbf{X} \rightarrow \mathbf{X} \cdot \llbracket C; \mathbf{X}, \mathbf{X}, \dots, \mathbf{X} \rrbracket$.

The Congruence Action: Example

Example ($\mathcal{P}_{2,2,2}$ revisited)

Consider again quadratic paths in \mathbb{R}^2 that were given by

$$X(t) = (x_{11}t + x_{12}t^2, x_{21}t + x_{22}t^2)^T = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} \cdot \begin{pmatrix} t \\ t^2 \end{pmatrix} = \mathbf{X} \cdot \begin{pmatrix} t \\ t^2 \end{pmatrix}$$

The **core tensor** is the signature matrix $\sigma^{(2)}(C_{mono}) = \begin{pmatrix} \frac{1}{2} & \frac{2}{3} \\ \frac{1}{3} & \frac{1}{2} \end{pmatrix}$.

Then $\sigma^{(2)}(X)$ is given by $\llbracket C; \mathbf{X}, \mathbf{X} \rrbracket = \mathbf{X} \cdot \sigma^{(2)}(C_{mono}) \cdot \mathbf{X}^T$

Indeed, we had computed that

$$\sigma_{ij}(X) = \frac{1}{2}x_{i1}x_{j1} + \frac{2}{3}x_{i1}x_{j2} + \frac{1}{3}x_{i2}x_{j1} + \frac{1}{2}x_{i2}x_{j2}.$$

The Skyline Path

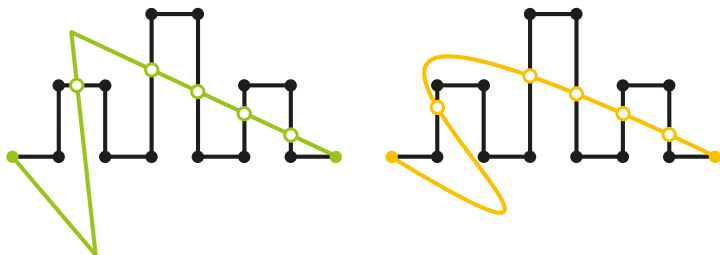
is an axis path with 13 steps in \mathbb{R}^2 , given by the columns of:

$$\mathbf{X} = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & -1 & 0 & 2 & 0 & -2 & 0 & 1 & 0 & -1 & 0 \end{bmatrix}.$$

Its $2 \times 2 \times 2$ signature tensor can be obtained by multiplying the core tensor C_{axis} of format $13 \times 13 \times 13$ with the 2×13 matrix \mathbf{X} on all three sides:

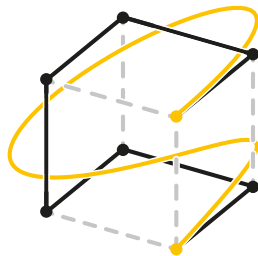
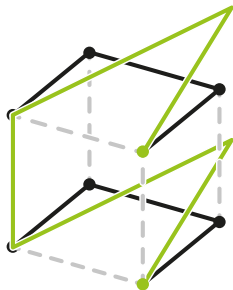
$$S_{\text{skyline}} = \llbracket C_{\text{axis}}; \mathbf{X}, \mathbf{X}, \mathbf{X} \rrbracket = \frac{1}{6} \left[\begin{array}{cc|cc} 343 & 0 & -84 & 18 \\ 84 & 18 & -36 & 0 \end{array} \right].$$

Three-step path and cubic path with the same signature tensor:



Klee-Minty Path

$$\mathbf{X} = \begin{bmatrix} 1 & 0 & -1 & 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 \end{bmatrix}.$$



$$\sigma^{(3)}(X) = \llbracket C_{\text{axis}}; \mathbf{X}, \mathbf{X}, \mathbf{X} \rrbracket = \frac{1}{6} \left[\begin{array}{ccc|ccc|ccc} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & -6 & -6 & 3 & 3 \\ 0 & 6 & 0 & -6 & 3 & -3 & 0 & 0 & 1 \end{array} \right]$$